

① MPHY-CC-6 Electrodynamics & Plasma Physics unit-1
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MAXWELL'S EQUATION OF ELECTROMAGNETIC WAVES

1. Maxwell's first equation: $\nabla \cdot \vec{D} = \rho$ or $\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$

It is Gauss's law of electrostatics.
 Where $\vec{D} = \epsilon_0 \vec{E}$, \vec{D} = Electric displacement or Electric flux density, \vec{E} = Electric field intensity, ρ = volume charge density. $\epsilon_0 \rightarrow$ permittivity of free space.

Integral form: $\nabla \cdot \vec{D} = \rho$

Integrating over volume

$$\int_V \nabla \cdot \vec{D} \, dV = \int_V \rho \, dV$$

But from Gauss divergence theorem, $\int_V \nabla \cdot \vec{D} \, dV = \oint_S \vec{D} \cdot d\vec{S}$

$$\text{so } \boxed{\oint_S \vec{D} \cdot d\vec{S} = \int_V \rho \, dV = q \text{ or } \oint_S \vec{E} \cdot d\vec{S} = \frac{1}{\epsilon_0} \int_V \rho \, dV = \frac{q}{\epsilon_0}}$$

It is Maxwell's first equation in 'integral form.

2. Maxwell's second equation: $\nabla \cdot \vec{B} = 0$ or $\nabla \cdot \vec{H} = 0$

It is Gauss's law of magnetism (Magnetostatics)

Where $\vec{B} = \mu_0 \vec{H}$, \vec{B} = magnetic field or magnetic flux density
 \vec{H} = magnetic field intensity, μ_0 = permeability of free space.

Integral form: $\nabla \cdot \vec{B} = 0$

Integrating over volume

$$\int_V \nabla \cdot \vec{B} \, dV = 0$$

But from Gauss divergence theorem, $\int_V \nabla \cdot \vec{B} \, dV = \oint_S \vec{B} \cdot d\vec{S}$

$$\text{so } \boxed{\oint_S \vec{B} \cdot d\vec{S} = 0} \text{ or } \oint_S \mu_0 \vec{H} \cdot d\vec{S} = 0 \therefore \vec{B} = \mu_0 \vec{H}$$

$$\Rightarrow \oint_S \vec{H} \cdot d\vec{S} = 0$$

Thus

$$\boxed{\oint_S \vec{B} \cdot d\vec{S} = 0 \text{ or } \oint_S \vec{H} \cdot d\vec{S} = 0}$$

It is Maxwell's second equation in integral form.

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3. Maxwell's third equation: $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

It is Faraday's law of electromagnetic induction.

Integral form: $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

Integrating both sides over surface S

$$\int_S (\nabla \times \vec{E}) \cdot d\vec{S} = - \int_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S}$$

But from Stoke's theorem, $\int_S (\nabla \times \vec{E}) \cdot d\vec{S} = \oint_L \vec{E} \cdot d\vec{l}$

$$\text{So } \boxed{\oint_L \vec{E} \cdot d\vec{l} = -\frac{\partial}{\partial t} \int_S \vec{B} \cdot d\vec{S} \Rightarrow \oint_L \vec{E} \cdot d\vec{l} = - \int_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S}}$$

It is Maxwell's third equation in integral form.

4. Maxwell's fourth equation: $\nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$

It is modified Ampere's circuital law

where \vec{J} = current density, $\frac{\partial \vec{D}}{\partial t}$ = Displacement current density.

Integral form: $\nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$

Integrating both sides over surface S

$$\int_S (\nabla \times \vec{H}) \cdot d\vec{S} = \int_S (\vec{J} + \frac{\partial \vec{D}}{\partial t}) \cdot d\vec{S}$$

But from Stoke's theorem, $\int_S (\nabla \times \vec{H}) \cdot d\vec{S} = \oint_L \vec{H} \cdot d\vec{l}$

$$\text{So } \boxed{\oint_L \vec{H} \cdot d\vec{l} = \int_S (\vec{J} + \frac{\partial \vec{D}}{\partial t}) \cdot d\vec{S} \text{ or } \oint_L \vec{B} \cdot d\vec{l} = \mu_0 \int_S (\vec{J} + \frac{\partial \vec{D}}{\partial t}) \cdot d\vec{S}}$$

It is Maxwell's four equation in integral form.

Thus Maxwell's equation of electromagnetism is

In differential form

In integral form

1. $\nabla \cdot \vec{D} = \rho$ or $\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$

1. $\oint_S \vec{D} \cdot d\vec{S} = \int_V \rho \cdot dV$ or $\oint_S \vec{E} \cdot d\vec{S} = \frac{1}{\epsilon_0} \int_V \rho \cdot dV$

2. $\nabla \cdot \vec{B} = 0$ or $\nabla \cdot \vec{H} = 0$

2. $\oint_S \vec{B} \cdot d\vec{S} = 0$ or $\oint_S \vec{H} \cdot d\vec{S} = 0$

3. $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

3. $\oint_L \vec{E} \cdot d\vec{l} = - \int_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S}$

4. $\nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$

4. $\oint_L \vec{H} \cdot d\vec{l} = \int_S (\vec{J} + \frac{\partial \vec{D}}{\partial t}) \cdot d\vec{S}$

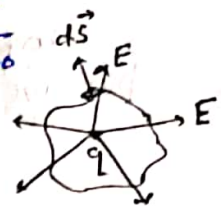
or $\oint_L \vec{B} \cdot d\vec{l} = \mu_0 \int_S (\vec{J} + \frac{\partial \vec{D}}{\partial t}) \cdot d\vec{S}$

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Derivation of Maxwell's equation of Electromagnetism.

Maxwell's first equation: $\nabla \cdot \vec{D} = \rho$ or $\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$

From Gauss's theorem of electrostatics, total electric flux through any closed surface is equal to total charge enclosed by the closed surface divided by ϵ_0 .



i.e. $\oint_S \vec{E} \cdot d\vec{S} = \frac{q}{\epsilon_0}$

Now volume charge density $\rho = \frac{dq}{dv} \Rightarrow dq = \rho dv$

$\Rightarrow q = \int_V \rho dv$

Thus $\oint_S \vec{E} \cdot d\vec{S} = \frac{1}{\epsilon_0} \int_V \rho dv$

But from Gauss divergence theorem,

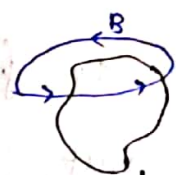
$\int_V (\nabla \cdot \vec{E}) dv = \oint_S \vec{E} \cdot d\vec{S}$

So $\int_V (\nabla \cdot \vec{E}) dv = \frac{1}{\epsilon_0} \int_V \rho dv \Rightarrow \int_V (\nabla \cdot \vec{E} - \frac{\rho}{\epsilon_0}) dv = 0$

$\Rightarrow \nabla \cdot \vec{E} - \frac{\rho}{\epsilon_0} = 0 \Rightarrow \boxed{\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}}$ or $\boxed{\nabla \cdot \vec{D} = \rho}$

Maxwell's second equation: $\nabla \cdot \vec{B} = 0$ or $\nabla \cdot \vec{H} = 0$ $\because \vec{D} = \epsilon_0 \vec{E}$

From Gauss's theorem of magnetism, total magnetic flux through any closed surface is equal to zero because magnetic field line is a closed continuous loop so total magnetic field lines entering a closed surface is equal to total magnetic field lines leaving the closed surface.



i.e. $\oint_S \vec{B} \cdot d\vec{S} = 0$

Using Gauss's divergence theorem, $\int_V (\nabla \cdot \vec{B}) dv = \oint_S \vec{B} \cdot d\vec{S}$

so $\int_V (\nabla \cdot \vec{B}) dv = 0 \Rightarrow \boxed{\nabla \cdot \vec{B} = 0}$ or $\boxed{\nabla \cdot \vec{H} = 0}$

$\because B = \mu_0 H$

Maxwell's third equation: $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

From Faraday's law of electromagnetic induction, the

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induced emf produced in a closed loop is equal to negative of time rate of change in magnetic flux linked with the closed loop.

$$\text{i.e., } e = - \frac{d\phi}{dt}$$

Emf (e) is defined as the work done in carrying unit positive charge (+1c) round a closed circuit.

$$\text{so } e = \oint \vec{E} \cdot d\vec{l} \Rightarrow \oint \vec{E} \cdot d\vec{l} = - \frac{\partial \phi}{\partial t}$$

But from Stoke's theorem, $\int_S (\nabla \times \vec{E}) \cdot d\vec{s} = \oint \vec{E} \cdot d\vec{l}$

$$\text{so } \int_S (\nabla \times \vec{E}) \cdot d\vec{s} = - \frac{\partial \phi}{\partial t} \quad \text{but } \phi = \int_S \vec{B} \cdot d\vec{s}$$

$$\text{so } \int_S (\nabla \times \vec{E}) \cdot d\vec{s} = - \frac{\partial}{\partial t} \int_S \vec{B} \cdot d\vec{s} \Rightarrow \int_S (\nabla \times \vec{E} + \frac{\delta \vec{B}}{\delta t}) \cdot d\vec{s} = 0$$

$$\Rightarrow \nabla \times \vec{E} + \frac{\delta \vec{B}}{\delta t} = 0 \Rightarrow \boxed{\nabla \times \vec{E} = - \frac{\delta \vec{B}}{\delta t}}$$

Maxwell's fourth equation: $\nabla \times \vec{H} = \vec{J} + \frac{\delta \vec{B}}{\delta t}$ concept of displacement current.

From Ampere's circuital law, line integration of magnetic field along any closed loop is equal to μ_0 times of total current passing through the surface bounded by the closed loop. i.e., $\oint \vec{B} \cdot d\vec{l} = \mu_0 I$

$$\text{but } I = \int_S \vec{J} \cdot d\vec{s} \quad \text{and } \vec{B} = \mu_0 \vec{H}$$

$$\text{so } \oint \mu_0 \vec{H} \cdot d\vec{l} = \mu_0 \int_S \vec{J} \cdot d\vec{s} \Rightarrow \oint \vec{H} \cdot d\vec{l} = \int_S \vec{J} \cdot d\vec{s}$$

But from Stoke's theorem, $\int_S (\nabla \times \vec{H}) \cdot d\vec{s} = \oint \vec{H} \cdot d\vec{l}$

$$\text{so } \int_S (\nabla \times \vec{H}) \cdot d\vec{s} = \int_S \vec{J} \cdot d\vec{s} \Rightarrow \int_S (\nabla \times \vec{H} - \vec{J}) \cdot d\vec{s} = 0$$

$$\Rightarrow \nabla \times \vec{H} - \vec{J} = 0 \Rightarrow \boxed{\nabla \times \vec{H} = \vec{J}} \quad (1)$$

The relation (1) stands only for steady closed current.

Now $\text{div}(\text{curl } \vec{H}) = 0$ because divergence of curl of any vector is zero.

$$\Rightarrow \text{div } \vec{J} = 0 \quad \text{--- (2)} \quad \therefore \nabla \times \vec{H} = \vec{J}$$

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From equation of continuity, $\text{div } \vec{J} = -\frac{\delta \rho}{\delta t}$ — (3)

From eqns (2) and (3), $\frac{\delta \rho}{\delta t} = 0 \Rightarrow \rho = \text{constant}$

Therefore eqn (1) is valid only for constant volume charge density. If volume charge density ρ be variable then $\text{div } \vec{J} \neq 0$

Maxwell suggested that eqn (1) is incomplete when volume charge density ρ is variable. For variable volume charge density ρ in space i.e., for varying field in space, Maxwell suggested that use $\vec{J} + \vec{J}_d$ in place of \vec{J} and this \vec{J}_d is known as displacement current density.

Hence eqn (1) will become $\vec{\nabla} \times \vec{H} = \vec{J} + \vec{J}_d$ — (4)

Since $\text{div}(\vec{\nabla} \times \vec{H}) = 0$ so $\text{div}(\vec{J} + \vec{J}_d) = 0$

$\Rightarrow \text{div } \vec{J} + \text{div } \vec{J}_d = 0 \Rightarrow \text{div } \vec{J}_d = -\text{div } \vec{J}$

$\Rightarrow \text{div } \vec{J}_d = -(-\frac{\delta \rho}{\delta t}) \because \text{div } \vec{J} = -\frac{\delta \rho}{\delta t}$ from eqn (3)

$\Rightarrow \text{div } \vec{J}_d = \frac{\delta \rho}{\delta t} \Rightarrow \vec{\nabla} \cdot \vec{J}_d = \frac{\delta}{\delta t}(\vec{\nabla} \cdot \vec{D})$ from Maxwell's first law $\rho = \vec{\nabla} \cdot \vec{D}$

$\Rightarrow \vec{\nabla} \cdot \vec{J}_d = \vec{\nabla} \cdot \frac{\delta \vec{D}}{\delta t} \Rightarrow \vec{\nabla} \cdot (\vec{J}_d - \frac{\delta \vec{D}}{\delta t}) = 0$

$\Rightarrow \vec{J}_d - \frac{\delta \vec{D}}{\delta t} = 0 \Rightarrow \boxed{\vec{J}_d = \frac{\delta \vec{D}}{\delta t}}$ It is formula for displacement current density.

put in eqn (4), we get

$$\boxed{\vec{\nabla} \times \vec{H} = \vec{J} + \frac{\delta \vec{D}}{\delta t}} \text{ or } \boxed{\vec{\nabla} \times \vec{B} = \mu_0 (\vec{J} + \frac{\delta \vec{D}}{\delta t})}$$

Displacement current $\boxed{I_d = \int_s \vec{J}_d \cdot d\vec{S}}$